



INPUT

OUTPUT

## 17.10 Medial-Axis Transform

**Input description:** A polygon or polyhedron  $P$ .

**Problem description:** What are the set of points within  $P$  that have more than one closest point on the boundary of  $P$ ?

**Discussion:** The medial-axis transformation is useful in *thinning* a polygon, or as is sometimes said, finding its *skeleton*. The goal is to extract a simple, robust representation of the shape of the polygon. The thinned versions of the letters A and B capture the essence of their shape, and would be relatively unaffected by changing the thickness of strokes or by adding font-dependent flourishes such as serifs. The skeleton also represents the center of the given shape, a property that leads to other applications like shape reconstruction and motion planning.

The medial-axis transformation of a polygon is always a tree, making it fairly easy to use dynamic programming to measure the “edit distance” between the skeleton of a known model and the skeleton of an unknown object. Whenever the two skeletons are close enough, we can classify the unknown object as an instance of our model. This technique has proven useful in computer vision and in optical character recognition. The skeleton of a polygon with holes (like the A and B) is not a tree but an embedded planar graph, but it remains easy to work with.

There are two distinct approaches to computing medial-axis transforms, depending upon whether your input is arbitrary geometric points or pixel images:

- *Geometric data* – Recall that the Voronoi diagram of a point set  $S$  (see Section 17.4 (page 576)) decomposes the plane into regions around each point  $s_i \in S$  such that points within the region around  $s_i$  are closer to  $s_i$  than to any other site in  $S$ . Similarly, the Voronoi diagram of a set of line segments  $L$  decomposes the plane into regions around each line segment  $l_i \in L$  such that all points within the region around  $l_i$  are closer to  $l_i$  than to any other site in  $L$ .

Any polygon is defined by a collection of line segments such that  $l_i$  shares a vertex with  $l_{i+1}$ . The medial-axis transform of a polygon  $P$  is simply the portion of the line-segment Voronoi diagram that lies within  $P$ . Any line-segment Voronoi diagram code thus suffices to do polygon thinning.

The *straight skeleton* is a structure related to the medial axis of a polygon, except that the bisectors are not equidistant to its defining edges but instead to the supporting lines of such edges. The straight skeleton, medial axis and Voronoi diagram are all identical for convex polygons, but in general skeleton bisectors may not be located in the center of the polygon. However, the straight skeleton is quite similar to a proper medial axis transform but is easier to compute. In particular, all edges in a straight skeleton are polygonal. See the Notes section for references with more details on how to compute it.

- *Image data* – Digitized images can be interpreted as points sitting at the lattice points on an integer grid. Thus, we could extract a polygonal description from boundaries in an image and feed it to the geometric algorithms just described. However, the internal vertices of the skeleton will most likely not lie at grid points. Geometric approaches to image processing problems often flounder because images are pixel-based and not continuous.

A direct pixel-based approach for constructing a skeleton implements the “brush fire” view of thinning. Imagine a fire burning along all edges of the polygon, racing inward at a constant speed. The skeleton is marked by all points where two or more fires meet. The resulting algorithm traverses all the boundary pixels of the object, identifies those vertices as being in the skeleton, deletes the rest of the boundary, and repeats. The algorithm terminates when all pixels are extreme, leaving an object only one or two pixels thick. When implemented properly, this takes linear time in the number of pixels in the image.

Algorithms that explicitly manipulate pixels tend to be easy to implement, because they avoid complicated data structures. However, the geometry doesn’t work out exactly right in such pixel-based approaches. For example, the skeleton of a polygon is no longer always a tree or even necessarily connected, and the points in the skeleton will be close-to-but-not-quite equidistant to two boundary edges. Since you are trying to do continuous geometry in a discrete world, there is no way to solve the problem completely. You just have to live with it.

**Implementations:** CGAL ([www.cgal.org](http://www.cgal.org)) includes a package for computing the straight skeleton of a polygon  $P$ . Associated with it are routines for constructing offset contours defining the polygonal regions within  $P$  whose points are at least distance  $d$  from the boundary.

*VRONI* [Hel01] is a robust and efficient program for computing Voronoi diagrams of line segments, points, and arcs in the plane. It can readily compute

medial-axis transforms of polygons since it can construct Voronoi diagrams of arbitrary line segments. *VRONI* has been tested on thousands of synthetic and real-world data sets, some with over a million vertices. For more information, see <http://www.cosy.sbg.ac.at/~held/projects/vroni/vroni.html>. Other programs for constructing Voronoi diagrams are discussed in Section 17.4 (page 576).

Programs that reconstruct or interpolate point clouds often are based on medial axis transforms. *Cocone* (<http://www.cse.ohio-state.edu/~tamaldehy/cocone.html>) constructs an approximate medial-axis transform of the polyhedral surface it interpolates from points in  $E^3$ . See [Dey06] for the theory behind *Cocone*. *Powercrust* [ACK01a, ACK01b] constructs a discrete approximation to the medial-axis transform, and then reconstructs the surface from this transform. When the point samples are sufficiently dense, the algorithm is guaranteed to produce a geometrically and topologically correct approximation to the surface. It is available at <http://www.cs.utexas.edu/users/amenta/powercrust/>.

**Notes:** For a comprehensive survey of thinning approaches in image processing, see [LLS92, Ogn93]. The medial axis transformation was introduced for shape similarity studies in biology [Blu67]. Applications of the medial-axis transformation in pattern recognition are discussed in [DHS00]. The medial axis transformation is fundamental to the power crust algorithm for surface reconstruction from sampled points; see [ACK01a, ACK01b]. Good expositions on the medial-axis transform include [dBvKOS00, O'R01, Pav82].

The medial-axis of a polygon can be computed in  $O(n \lg n)$  time for arbitrary  $n$ -gons [Lee82], although linear-time algorithms exist for convex polygons [AGSS89]. An  $O(n \lg n)$  algorithm for constructing medial-axis transforms in curved regions was given by Kirkpatrick [Kir79].

Straight skeletons were introduced in [AAAG95], with a subquadratic algorithm due to [EE99]. See [LD03] for an interesting application of straight skeletons to defining the roof structures in virtual building models.

**Related Problems:** Voronoi diagrams (see page 576), Minkowski sum (see page 617).